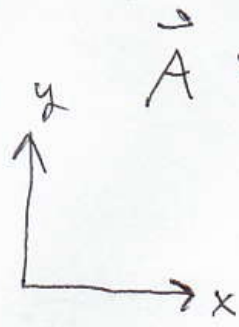
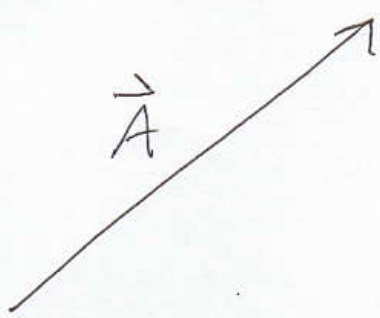


2D vectors: \vec{A} has magnitude =
and direction

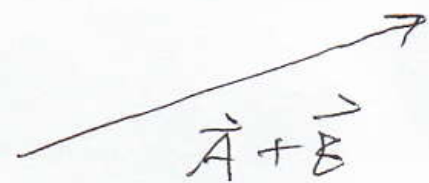
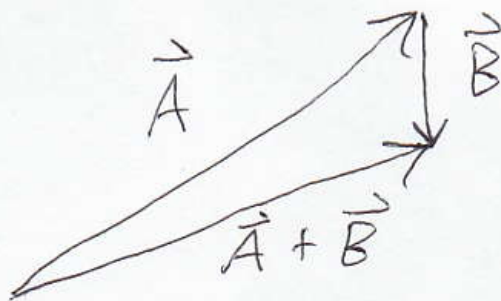
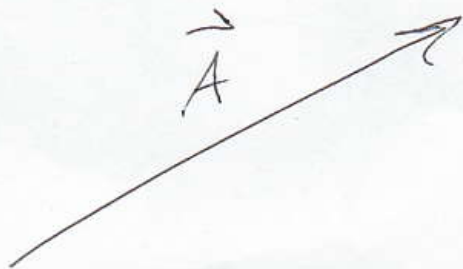


$$\vec{A} = (A_x, A_y)$$

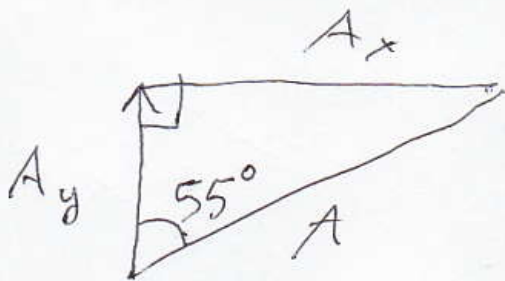
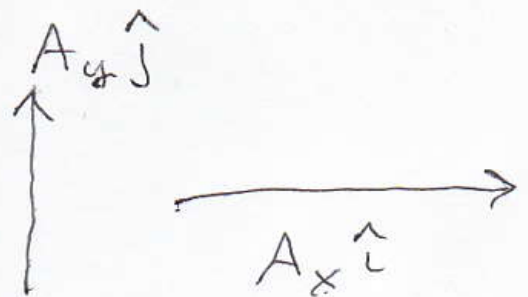
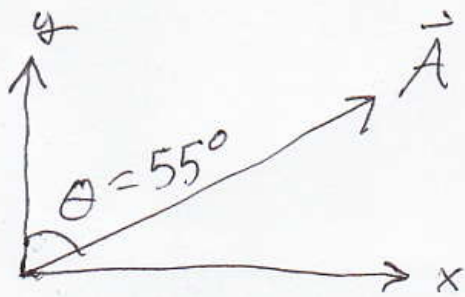
$$\vec{A} = A_x \hat{i} + A_y \hat{j}$$

$$\hat{i} = (1, 0) \quad \hat{j} = (0, 1)$$

Add vectors "head to tail":

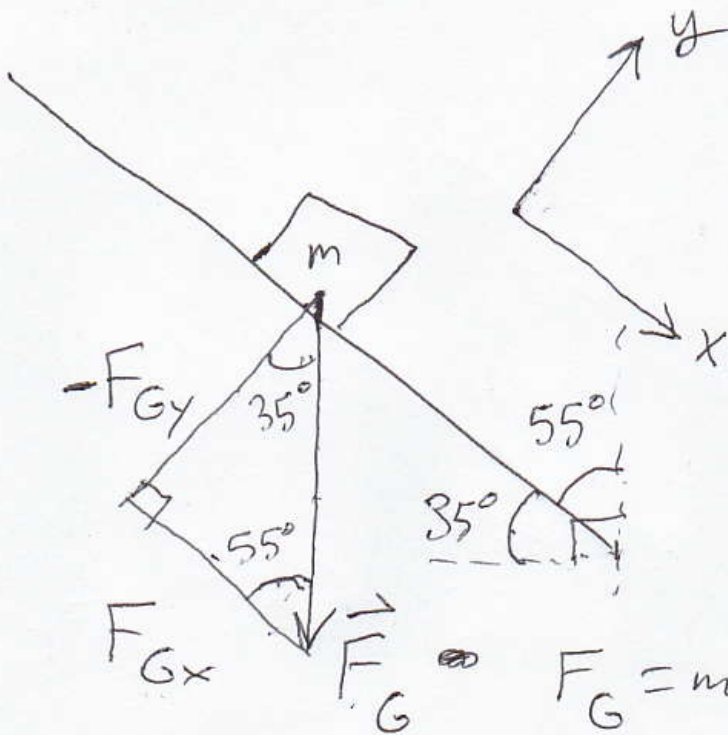


$$\vec{A} + \vec{B} = (A_x + B_x, A_y + B_y)$$



$$A_x = A \sin 55^\circ$$

$$A_y = A \cos 55^\circ$$



$$F_G = mg$$

magnitude

$$g = 9.80 \text{ m/s}^2$$

$$F_{Gx} = F_G \sin 35^\circ = mg \sin 35^\circ$$

no friction $\Rightarrow a = \frac{F_{Gx}}{m} = g \sin 35^\circ$

Constant acceleration kinematics:

$$x = \frac{1}{2} a_x t^2 + v_{ix} + x_i$$

$$y = \frac{1}{2} a_y t^2 + v_{iy} + y_i$$

(x_i, y_i) = initial position at $t=0$

$\vec{v}_i = (v_{ix}, v_{iy})$ = initial velocity at $t=0$

→ Choose coordinate system

to get $(x_i, y_i) = (0, 0)$

and maybe $a_x = 0$ or $a_y = 0$

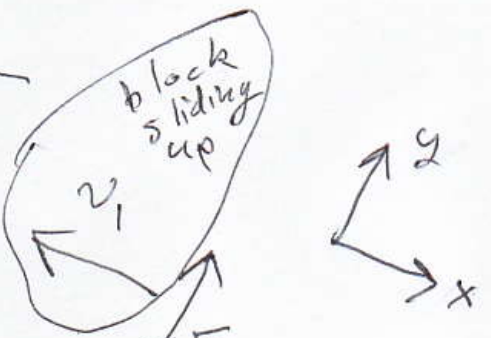
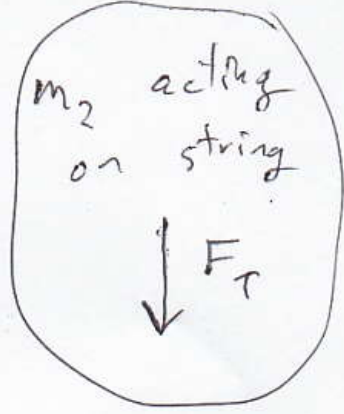
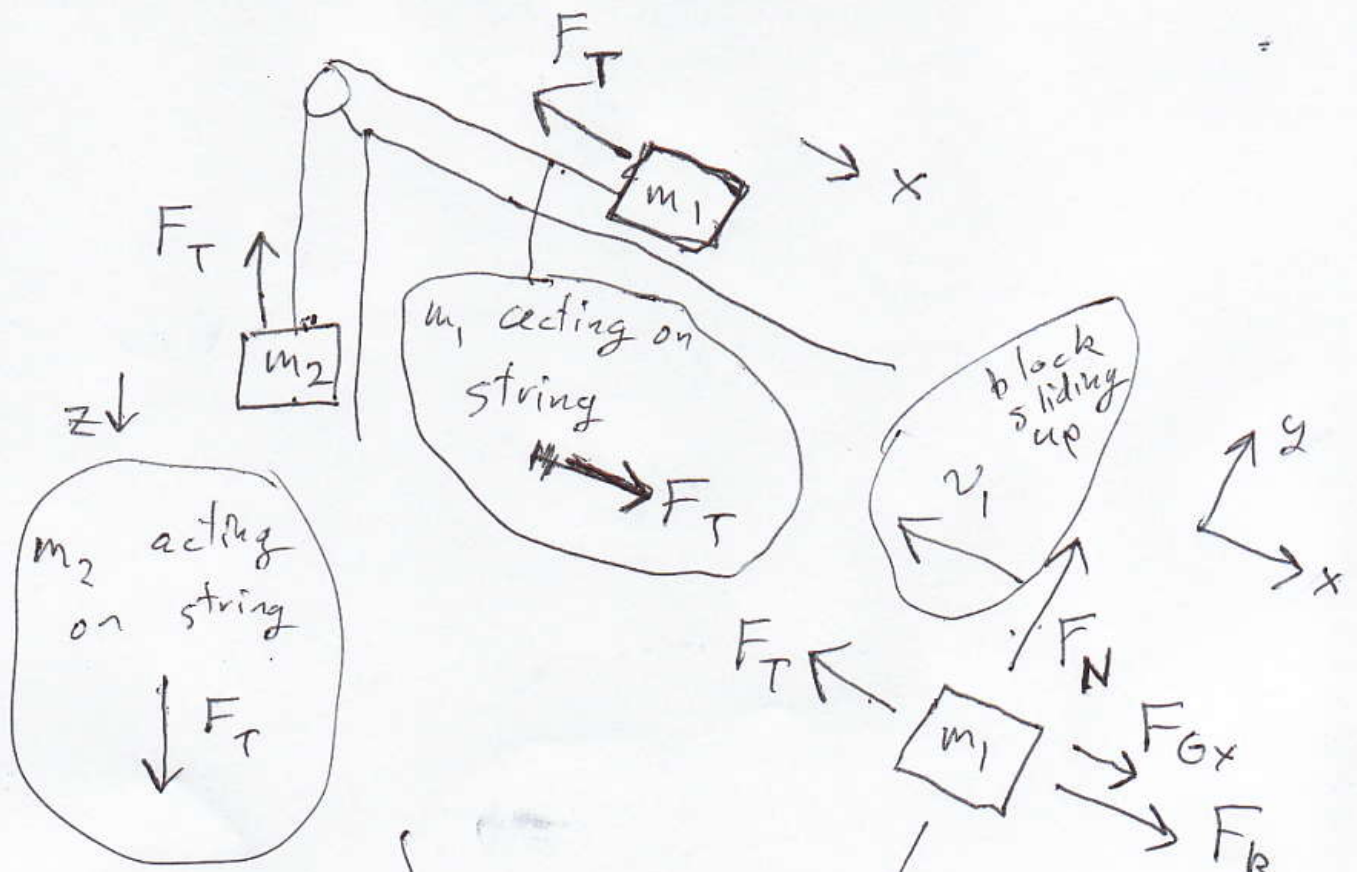
→ These imply some other useful equations:

$$v_x = a_x t + v_{ix}$$

$$v_y = a_y t + v_{iy}$$

$$v_x^2 = v_{ix}^2 + 2a_x(x - x_i)$$

$$v_y^2 = v_{iy}^2 + 2a_y(y - y_i)$$

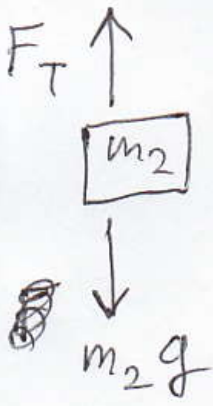


$$-F_{Gy} = F_N = m_1 g \cos \theta$$
 because $a_{ly} = 0$

$$F_{Gx} = m_1 g \sin \theta$$

$$(5.1) \quad F_k = \mu_k F_N = m_1 g \mu_k \cos \theta$$

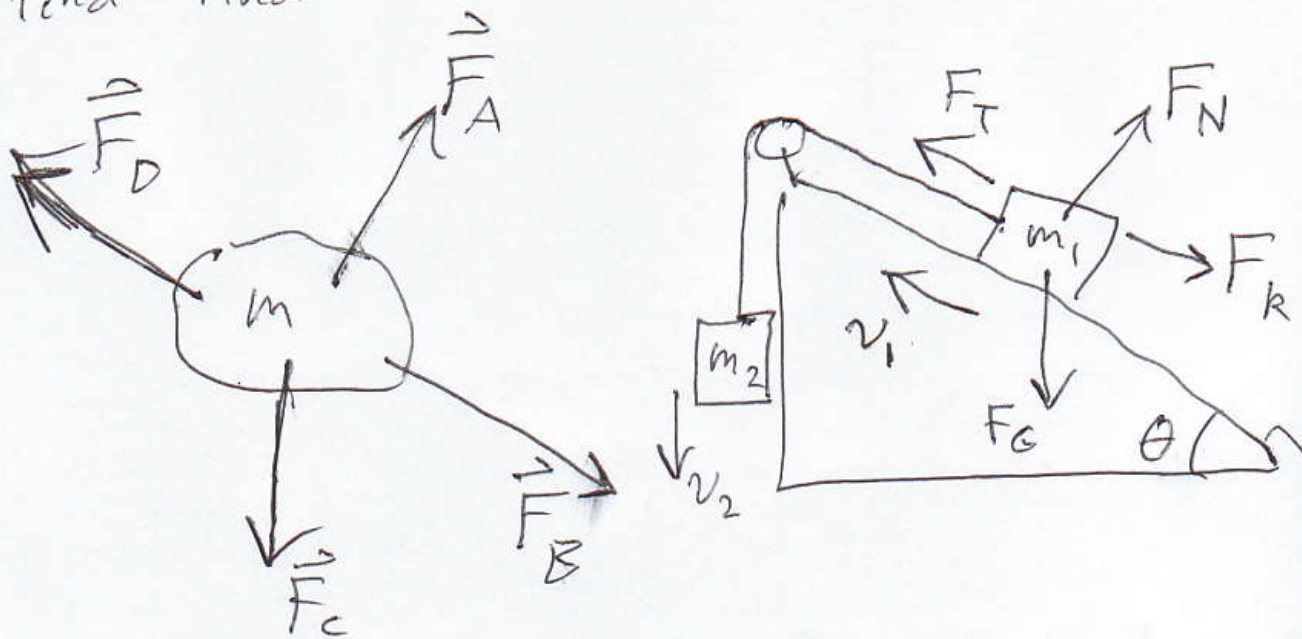
$$m a_{1x} = -F_T + F_{Gx} + F_k$$



$$m_2 a_{2z} = m_2 g - F_T$$

$$a_{2z} = -a_{1x}$$

You may need to find acceleration given forces using Newton's Laws. (Or find a force given acceleration)



$$m\vec{a} = \sum \vec{F} = \vec{F}_A + \vec{F}_B + \vec{F}_C + \vec{F}_D$$

↑
sum
Newton's 2nd Law

$$\mu_k = 0.15 \quad m_1 = 0.500 \text{ kg}$$

$$\theta = (30 \times 10)^\circ \quad m_2 = 0.300 \text{ kg}$$

What is acceleration of m_1 ?

Newton's 3rd: Forces come in pairs:

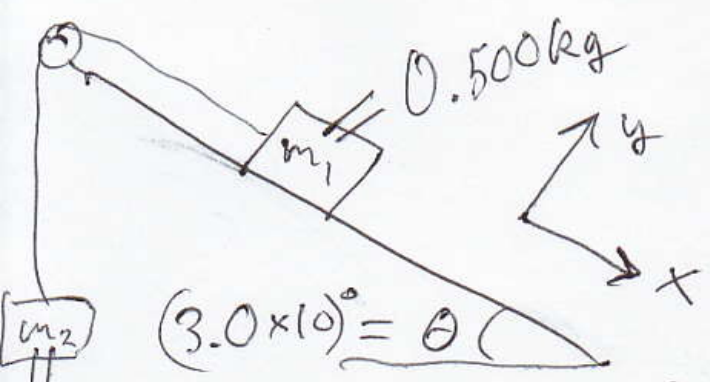
$$\left\{ \begin{aligned} -m_2 a_{1x} &= m_2 g - F_T \end{aligned} \right.$$

$$\left\{ \begin{aligned} m_1 a_{1x} &= -F_T + F_{Gx} + F_k \\ m_2 a_{1x} &= F_T - m_2 g \end{aligned} \right.$$

add

$$(m_1 + m_2) a_{1x} = F_{Gx} + F_k - m_2 g$$

$$a_{1x} = \frac{F_{Gx} + F_k - m_2 g}{m_1 + m_2}$$



$$a_{1y} = 0 \Rightarrow |a_{1x}| = a_1$$

$$g = 9.80 \text{ m/s}^2$$

$$a_{1x} = \frac{m_1 g \sin \theta + m_1 g \mu_k \cos \theta - m_2 g}{m_1 + m_2}$$

$\mu_k = \text{coefficient of kinetic friction} = 0.15$

$$a_{1x} = 1.8 \times 10^{-1} \text{ m/s}^2 \Rightarrow a_1 = |a_{1x}| = a_{1x}$$

$$a_1 = 1.8 \times 10^{-1} \text{ m/s}^2 \text{ down the ramp}$$

If $m_2 = 1.000 \text{ kg}$, $a_{1x} = -4.5 \text{ m/s}^2 \Downarrow$
 $a_1 = 4.5 \text{ m/s}^2 \text{ up the ramp}$

$$F_k = \mu_k F_N$$

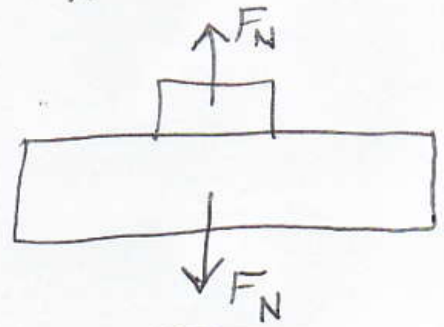
kinetic friction

$$F_s \leq \mu_s F_N$$

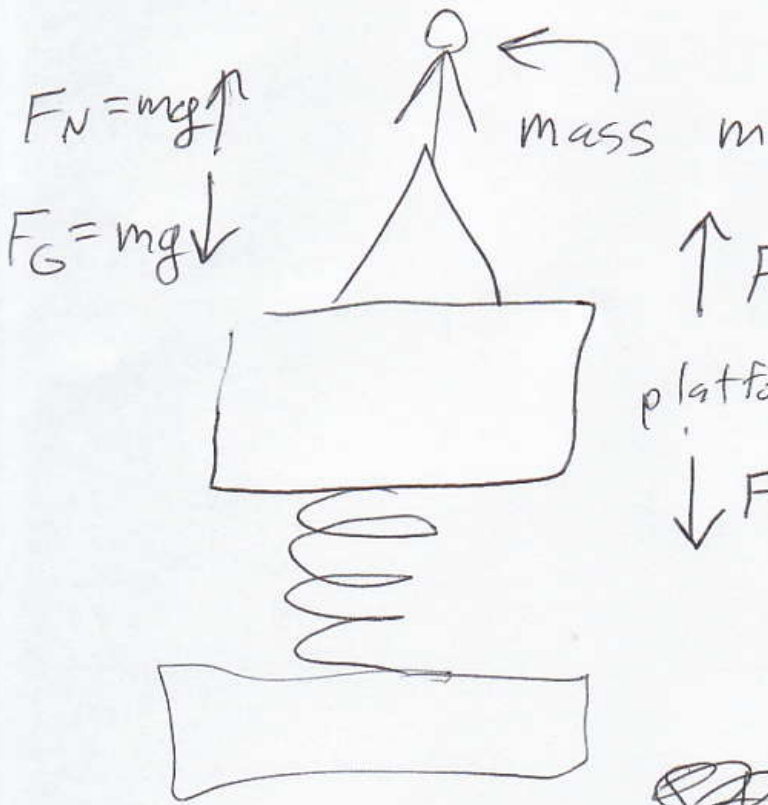
static friction

only depend
on two
touching
materials

$F_N =$ normal force



Q. 15 of Ch. 4 (p. 103)



15a) yes

15b) no

$\uparrow F_{sp}$ spring force = mg
platform at rest

$\downarrow F_N = mg$

because
platform
not
accelerating

~~Scale~~ Scale measures

weight is a force,
not a mass

F_s , which

equals weight mg .

1 pound = 4.44822 N is a force unit