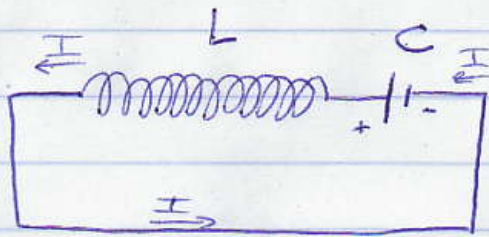


LAST TIME



$$T = \frac{2\pi}{\omega} = 2\pi\sqrt{LC}$$

$$\Phi = A \cos(\omega t + \phi)$$

$$\downarrow$$

$$\Phi_{\max}$$

$$\downarrow$$

$$\omega = \frac{1}{\sqrt{LC}}$$



→ t

$A, \phi$  depend on initial condition.

$$I = -\frac{dQ}{dt} = A\omega \sin(\omega t + \phi)$$

\* ENERGY in CAPACITOR

$$\frac{Q^2}{2C} = U_C$$

IN INDUCTOR  $\frac{1}{2}LI^2 = U_L$

$$A\omega \cos\left(\omega t + \phi - \frac{\pi}{2}\right)$$

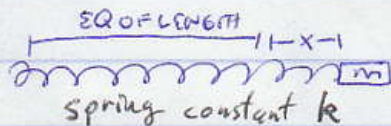
↑  
I = I<sub>max</sub> at times after  $\frac{T}{4}$

$$\frac{T}{4}$$

$$Q = Q_{\max}$$

$$\frac{\pi}{2} = \frac{2\pi}{4} = 90^\circ = \frac{1}{4} \text{ of a revolution}$$

~ COMPARE TO SPRING:

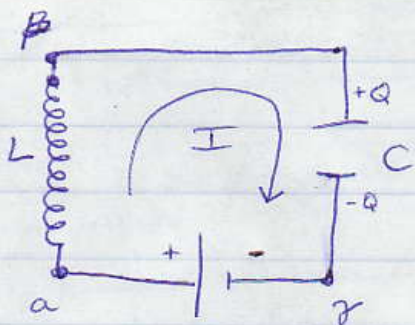


$$\frac{1}{2}kx^2 = U_{\text{spring}}$$

$$\frac{1}{2}mv^2 = K = \text{kinetic energy}$$

$$v = \frac{dx}{dt}$$

LC + dc source  
 $\underbrace{\hspace{2cm}}_{\text{EQ battery}}$

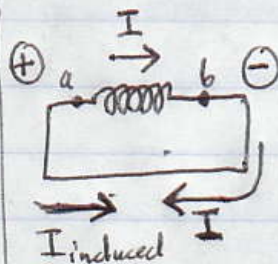


Battery emf =  $V_{ac} = V_a - V_c$

$\mathcal{E}$  opposes  $\frac{dI}{dt}$

$$\mathcal{E} = -L \frac{dI}{dt}$$

$\frac{dI}{dt} > 0$

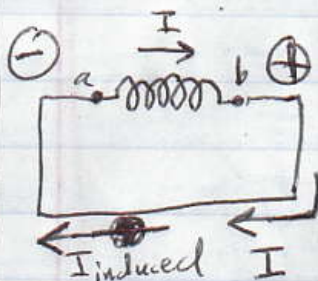


$$V_{ab} = V_a - V_b$$

$$V_{ab} = -\mathcal{E}$$

$$V_{ab} = +L \frac{dI}{dt}$$

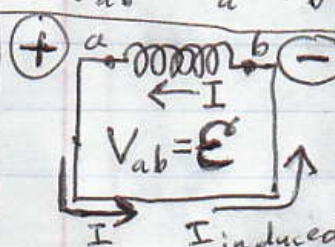
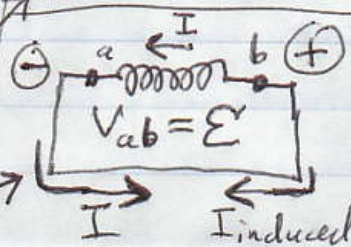
$\frac{dI}{dt} < 0$



$$V_{ab} = -\mathcal{E}$$

$$V_{ab} = +L \frac{dI}{dt}$$

$$V_{ab} = V_a - V_b$$



KIRCHOFF'S LAW (LOOP)

$$0 = V_{\alpha\beta} + V_{\beta\gamma} + V_{\gamma\alpha}$$

$$0 = +L \frac{dI}{dt} + \frac{Q}{C} - V_{\alpha\gamma}$$

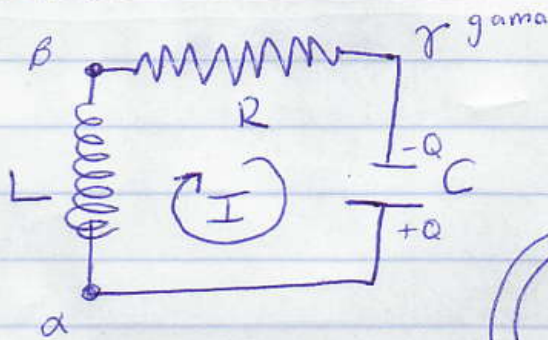
w/out battery =  $0 = -L \frac{dI}{dt} + \frac{Q}{C}$

SOLUTION :  $Q = A \cos(\omega t + \phi) + C V_{\alpha\gamma}$

$$I = \frac{dQ}{dt} = -A \omega \sin(\omega t + \phi) = A \omega \cos(\omega t + \phi + \frac{\pi}{2})$$

$I_{max}$

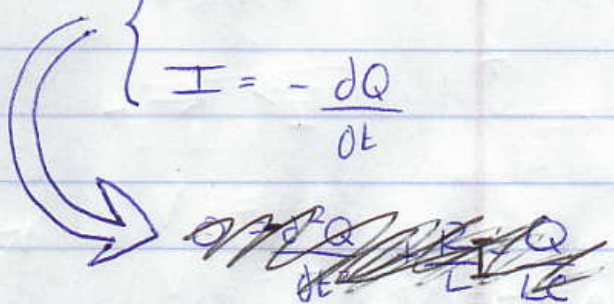
LRC circuit



$$0 = V_{\alpha\beta} + V_{\beta\gamma} + V_{\gamma\alpha}$$

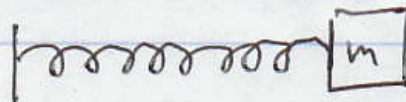
$$0 = +L \frac{dI}{dt} + IR - \frac{Q}{C}$$

$$I = -\frac{dQ}{dt}$$



$$0 = \frac{d^2 Q}{dt^2} + \frac{R}{L} \frac{dQ}{dt} + \frac{Q}{LC}$$

Compare to spring:



$$0 = \frac{d^2 x}{dt^2} + \left(\frac{b}{m}\right) \frac{dx}{dt} + \left(\frac{k}{m}\right) x$$

$k$  = spring constant  
 $b$  = "damping term"

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$$\Phi = Ae^{-t/\tau} \cos(\omega_d t + \phi)$$

$$\tau = \frac{L}{2R}$$

$$\omega_d = \sqrt{\omega^2 - \left(\frac{1}{\tau}\right)^2} < \omega$$

$$\uparrow \omega = \frac{1}{\sqrt{LC}}$$

UNDERDAMPED

$$\omega > \frac{1}{\tau}$$

$$\Phi = (A + Bt)e^{-t/\tau}$$

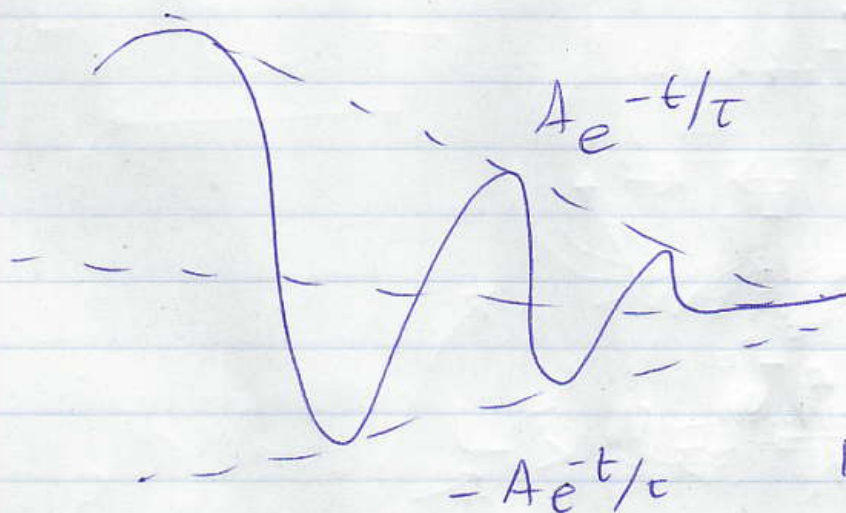
CRITICALLY DAMPED

$$\omega = \frac{1}{\tau}$$

$$Q = e^{-t/\tau} (A e^{t\sqrt{1/\tau^2 - \omega^2}} + B e^{-t\sqrt{1/\tau^2 - \omega^2}})$$

OVERDAMPED

$$\omega < \frac{1}{\tau}$$



If you add a battery with voltage  $V$ , then you add  $\pm CV$  to  $Q$



SOURCE OF AC CURRENT

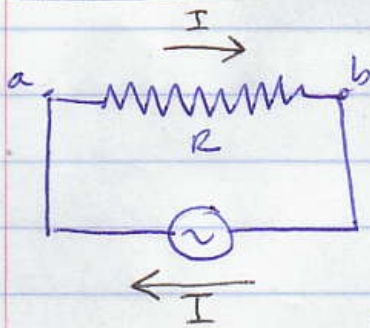
$$I = I_0 \cos(\omega t) \quad I_0 \text{ or } I_{\text{max}} \text{ is given}$$

$I_{\text{max}}$

120 Hz 2 in wall outlet

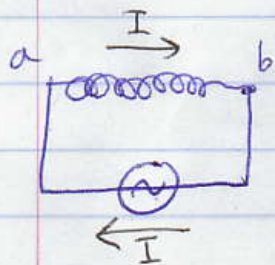


$$I_{\text{rms}} = \sqrt{\frac{1}{T} \int_0^T I^2 dt} = \frac{I_{\text{max}}}{\sqrt{2}} = \frac{I_0}{\sqrt{2}}$$



$$V_{ab} = IR = I_0 R \cos \omega t$$

$$R = \frac{V_{ab}}{I_0} = \frac{V_{\text{max}}}{I_{\text{max}}} = \frac{V_{\text{max}}/\sqrt{2}}{I_{\text{max}}/\sqrt{2}} = \frac{V_{\text{rms}}}{I_{\text{rms}}}$$



$$V_{ab} = L \frac{dI}{dt} = -\omega L I_0 \sin(\omega t) = V_{\text{max}} \cos(\omega t + \frac{\pi}{2})$$

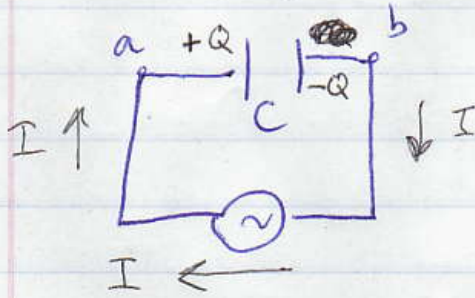
$$X_L = \frac{V_{\text{rms}}}{I_{\text{rms}}} = \frac{V_{\text{max}}/\sqrt{2}}{I_{\text{max}}/\sqrt{2}} = \frac{\omega L I_0}{I_0} = \omega L$$

↑  
Peak positive V across inductors happens  $\frac{T}{4}$  before peak positive current voltage leads current by  $90^\circ$

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$$I = \frac{dQ}{dt}$$

Assuming  $Q=0$  when  $t=0$



$$V_{ab} = \frac{Q}{C} = \frac{1}{C} \int_0^t I_0 \cos(\omega t) dt$$

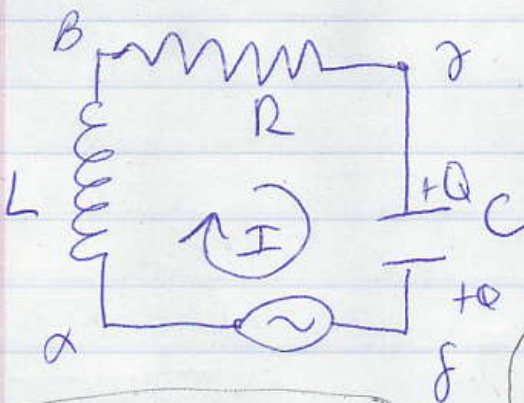
$$V_{ab} = \frac{I_0}{\omega C} \sin(\omega t)$$

$$X_C = \frac{V_{rms}}{I_{rms}} = \frac{1}{\omega C}$$

$$V_{ab} = \frac{I_0}{\omega C} \sin(\omega t) = \frac{I_0}{\omega C} \cos(\omega t - \frac{\pi}{2})$$

$\uparrow$   
 $V_{max}$   
 $\uparrow$   
 $V$  LAGS current by  $90^\circ$

LRC circuit w/ ac source



$$\begin{cases} V_{\alpha\delta} = V_{\alpha\beta} + V_{\beta\gamma} + V_{\gamma\delta} \\ V_{\alpha\delta} = V_{max} \cos(\omega t + \phi) \end{cases}$$

$$Z = \frac{V_{rms}}{I_{rms}} = \frac{V_{max}}{I_{max}} = \sqrt{R^2 + (X_C - X_L)^2}$$

$$\sqrt{R^2 + (X_L - X_C)^2}$$

Assuming  $Q=0$  when  $t=0$

$$\phi = \tan^{-1} \left( \frac{X_L - X_C}{R} \right)$$

$$V_{\alpha\beta} = X_L I_0 \cos(\omega t + \frac{\pi}{2})$$

$$V_{\beta\gamma} = R I_0 \cos(\omega t)$$

$$V_{\gamma\delta} = X_C I_0 \cos(\omega t - \frac{\pi}{2})$$

$$I = \frac{dQ}{dt}$$