

Part I

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix} :$$

Rotation
(of 180° around
x-axis)

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} :$$

Reflection
(about the plane
 $y=0$)

$$\begin{bmatrix} 1 & 5 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} :$$

skew

$$\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} :$$

Rotation
(90° counterclockwise)

$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} :$$

Reflection
(about line $x=y$)

$$\begin{bmatrix} 3 & 0 \\ 0 & 4 \end{bmatrix} :$$

scale change

$\begin{bmatrix} \sqrt{3}/2 & -1/2 \\ 1/2 & \sqrt{3}/2 \end{bmatrix}$: rotation ~~30~~ $(30^\circ \text{ counterclockwise})$

$\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$: none of the above

$\begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix}$: none of the above

$\begin{bmatrix} 3/5 & 4/5 \\ 4/5 & -1/5 \end{bmatrix}$: none of the above

One way to prove the "none of the aboves":

They don't have the $\begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix}$ form;

they don't have skew $\begin{bmatrix} 1 & 0 \\ a & 1 \end{bmatrix}$ or $\begin{bmatrix} 1 & a \\ 0 & 1 \end{bmatrix}$

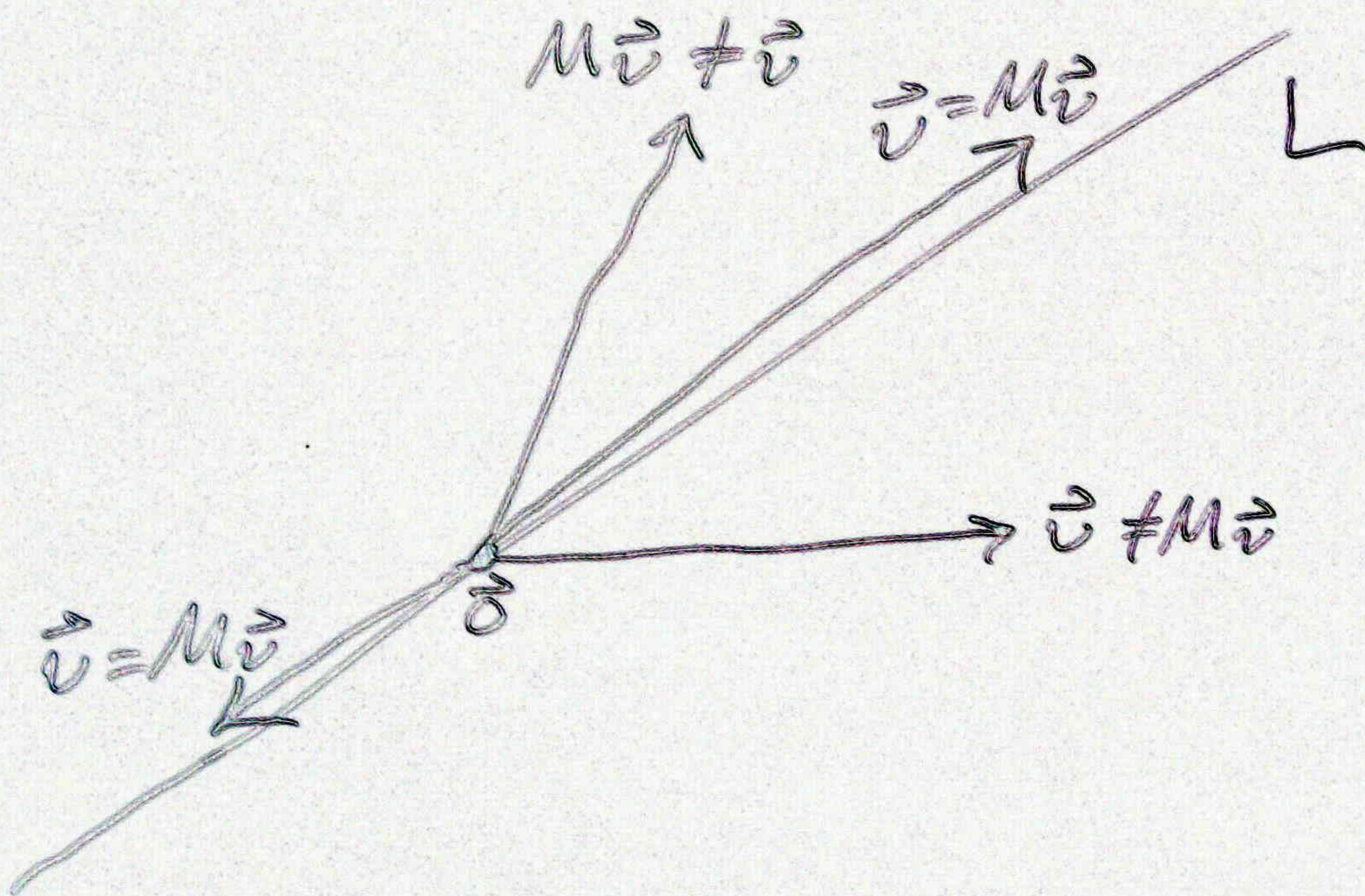
form; they don't have the scale change

$\begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix}$ (with $a, b > 0$) form. Also, they

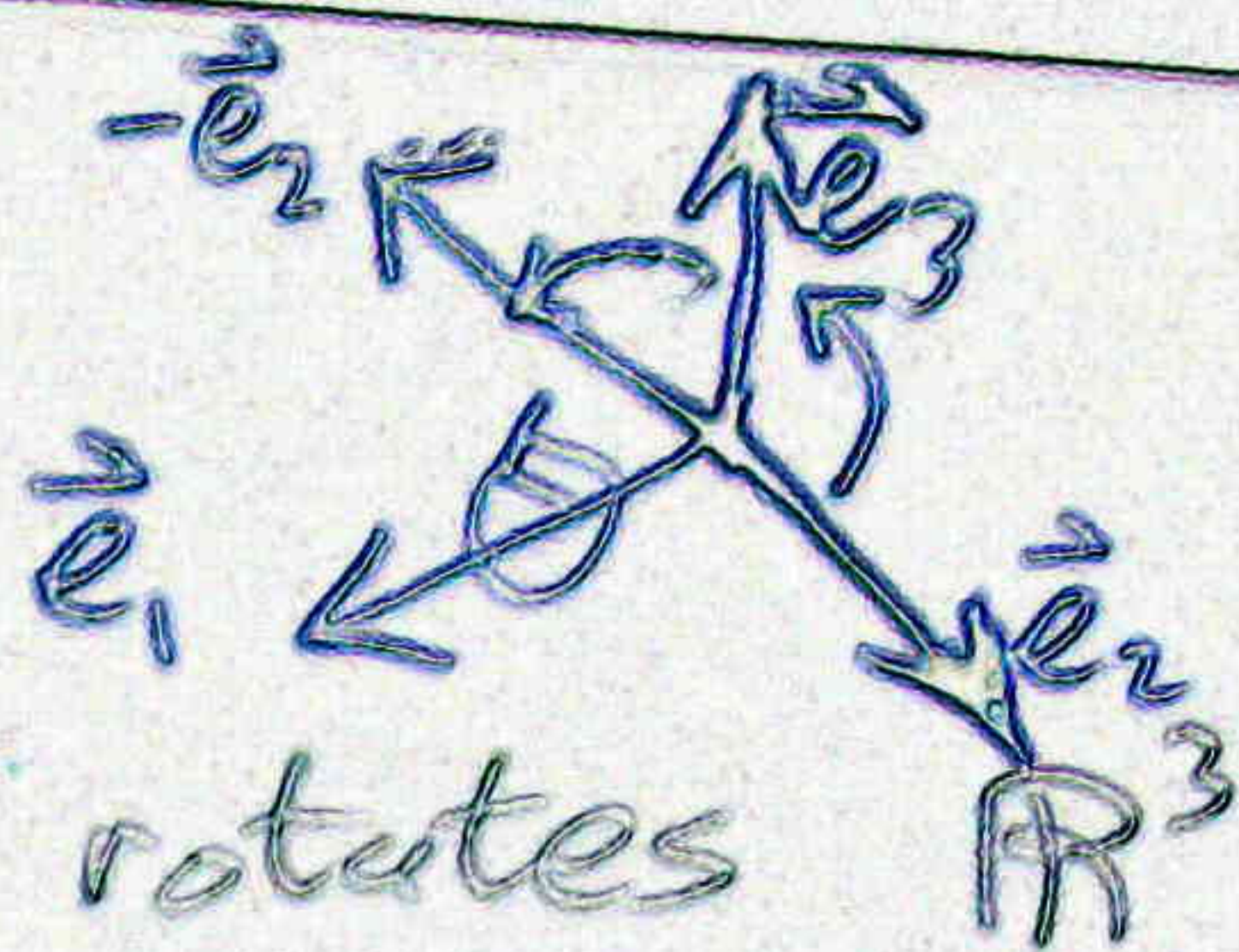
are not reflections about lines because in all three cases, letting M be the matrix, $M\vec{v} = \vec{v} \Leftrightarrow \vec{v} \in \ker(M - I)$

$\Leftrightarrow \vec{v} = \vec{0}$ can be shown using G-J elimination.

A reflection M about a line L satisfies $M\vec{v} = \vec{v}$ for exactly those $\vec{v}$ in L . $\{\vec{0}\}$ is not a line.



Part II



$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{bmatrix}$$

$$\vec{e}_1, \vec{e}_3, -\vec{e}_2$$

rotates $\mathbb{R}^3$ 90° ccw
around the $+x$ -axis

(sending $\vec{e}_2$ to $\vec{e}_3$

$\vec{e}_3$ to $-\vec{e}_2$
 $\vec{e}_1$ to $\vec{e}_1$)

(Note: $\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} \cos \frac{\pi}{2} & -\sin \frac{\pi}{2} \\ \sin \frac{\pi}{2} & \cos \frac{\pi}{2} \end{bmatrix}$ & $\vec{e}_3$ to $-\vec{e}_2$
 $\vec{e}_1$ to $\vec{e}_1$)

$$P = \{(x, y, z) : x + 2y + 3z = 0\} = \ker([1 \ 2 \ 3])$$

$$= \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} : \begin{array}{l} x = -2y - 3z \\ y = y \\ z = z \end{array} \right\} = \text{span} \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -3 \\ 0 \\ 1 \end{bmatrix} \right\}$$

Let $\vec{v}_1 = \vec{u}_1$ & $\vec{v}_2 = \vec{u}_2 - \frac{\vec{v}_1 \cdot \vec{u}_2}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1$ to get

an orthogonal basis of P .

$$\vec{v}_2 = \begin{bmatrix} -3 \\ 0 \\ 1 \end{bmatrix} - \frac{6}{5} \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0.6 \\ -1.2 \\ 1 \end{bmatrix}$$

The reflection R about P is given by

$$\begin{aligned} R\vec{w} &= 2\text{proj}_P \vec{w} - \vec{w} = 2(\text{proj}_{\vec{v}_1} \vec{w} + \text{proj}_{\vec{v}_2} \vec{w}) - \vec{w} \\ &= 2 \left(\frac{\vec{v}_1 \cdot \vec{w}}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 + \frac{\vec{v}_2 \cdot \vec{w}}{\vec{v}_2 \cdot \vec{v}_2} \vec{v}_2 \right) - \vec{w} \end{aligned}$$

$$R\vec{e}_1 = 2\left(\frac{-2}{5}\right)\begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + 2\left(\frac{0.6}{2.8}\right)\begin{bmatrix} 0.6 \\ -1.2 \\ 1 \end{bmatrix} - \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} 6/7 \\ -46/35 \\ 3/7 \end{bmatrix}$$

$$R\vec{e}_2 = 2\left(\frac{1}{5}\right)\begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + 2\left(\frac{-1.2}{2.8}\right)\begin{bmatrix} 0.6 \\ -1.2 \\ 1 \end{bmatrix} - \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} 2/7 \\ -13/35 \\ -6/7 \end{bmatrix}$$

$$R\vec{e}_3 = 2\left(\frac{0}{5}\right)\begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + 2\left(\frac{1}{2.8}\right)\begin{bmatrix} 0.6 \\ -1.2 \\ 1 \end{bmatrix} - \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} 3/7 \\ -6/7 \\ 2/7 \end{bmatrix}$$

The matrix $\begin{bmatrix} R\vec{e}_1 & R\vec{e}_2 & R\vec{e}_3 \end{bmatrix}$ of R

is

$$\begin{bmatrix} 6/7 & 2/7 & 3/7 \\ -46/35 & -13/35 & -6/7 \\ 3/7 & -6/7 & 2/7 \end{bmatrix}$$

45° ccw rotation about $+z$ -axis:

$$\begin{bmatrix} \cos \pi/4 & -\sin \pi/4 & 0 \\ \sin \pi/4 & \cos \pi/4 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1/\sqrt{2} & -1/\sqrt{2} & 0 \\ 1/\sqrt{2} & 1/\sqrt{2} & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

If R reflects $\mathbb{R}^2$ about $L = \text{span}\left\{\begin{bmatrix} 3 \\ -4 \end{bmatrix}\right\}$,
then $R\vec{w} = 2\left(\frac{\vec{v} \cdot \vec{w}}{\vec{v} \cdot \vec{v}}\right)\vec{v} - \vec{w}$ where $\vec{v} = \begin{bmatrix} 3 \\ -4 \end{bmatrix}$.

$$R\vec{e}_1 = 2\left(\frac{3}{25}\right)\begin{bmatrix} 3 \\ -4 \end{bmatrix} - \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -7/25 \\ -24/25 \end{bmatrix}$$

$$R\vec{e}_2 = 2\left(\frac{-4}{25}\right)\begin{bmatrix} 3 \\ -4 \end{bmatrix} - \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} -24/25 \\ 7/25 \end{bmatrix}$$

$$R = [R\vec{e}_1 \quad R\vec{e}_2] = \begin{bmatrix} -7/25 & -24/25 \\ -24/25 & 7/25 \end{bmatrix}$$

120° ccw rotation about $+y$ -axis:

$$\begin{bmatrix} \cos 2\pi/3 & 0 & \sin 2\pi/3 \\ 0 & 1 & 0 \\ -\sin 2\pi/3 & 0 & \cos 2\pi/3 \end{bmatrix} = \begin{bmatrix} -1/2 & 0 & +\sqrt{3}/2 \\ 0 & +1 & 0 \\ +\sqrt{3}/2 & 0 & -1/2 \end{bmatrix}$$