

3D #4 "only if" proof:

Choose a basis w_1, \dots, w_m of range T_2 .
Choose $v_i \in V$ such that $w_i = T_2 v_i$ for each $i \leq m$. Let $x_i = T_1 v_i$ for $i \leq m$.

Claim, x_1, \dots, x_m is a basis of range T_1 .

$$\begin{aligned} \text{Proof, } \dim \text{range } T_1 &= \dim W - \dim \text{null } T_1 \\ &= \dim W - \dim \text{null } T_2 \\ &= \dim \text{range } T_2 \\ &= m. \end{aligned}$$

So, it's enough to verify independence.

$$\begin{aligned} 0 &= a_1 x_1 + \dots + a_m x_m \\ \Rightarrow 0 &= a_1 T_1 v_1 + \dots + a_m T_1 v_m = T_1 (a_1 v_1 + \dots + a_m v_m) \\ \Rightarrow a_1 v_1 + \dots + a_m v_m &\in \text{null } T_1 = \text{null } T_2 \\ \Rightarrow 0 &= T_2 (a_1 v_1 + \dots + a_m v_m) = a_1 w_1 + \dots + a_m w_m \\ \Rightarrow 0 &= a_1 = \dots = a_m \end{aligned}$$

because w_1, \dots, w_m is lin. indep. ■

Extend w_1, \dots, w_m to a basis w_1, \dots, w_n of W ;
extend x_1, \dots, x_m to a basis x_1, \dots, x_n of W .
Define $S \in \mathcal{L}(W)$ by $S w_i = x_i$.
Then S^{-1} exists; it is the map in $\mathcal{L}(W)$ sending x_i to w_i . Given $v \in V$, we next verify that $S T_2 v = T_1 v$. Let $T_2 v = b_1 w_1 + \dots + b_m w_m$. Then $S T_2 v = b_1 x_1 + \dots + b_m x_m = T_1 (b_1 v_1 + \dots + b_m v_m)$. Therefore, it's enough to prove $T_1 v = T_1 y$ where $y = b_1 v_1 + \dots + b_m v_m$.

$$\begin{aligned} T_1 v = T_1 y &\iff T_1(v-y) = 0 \\ &\iff v-y \in \text{null } T_1 \\ &\iff v-y \in \text{null } T_2 \\ &\iff T_2(v-y) = 0 \\ &\iff T_2 v = T_2 y. \end{aligned}$$

So, proving $T_2 v = T_2 y$ is enough.

$$T_2 y = b_1 T_2 v_1 + \dots + b_m T_2 v_m = b_1 w_1 + \dots = T_2 v. \quad \blacksquare$$