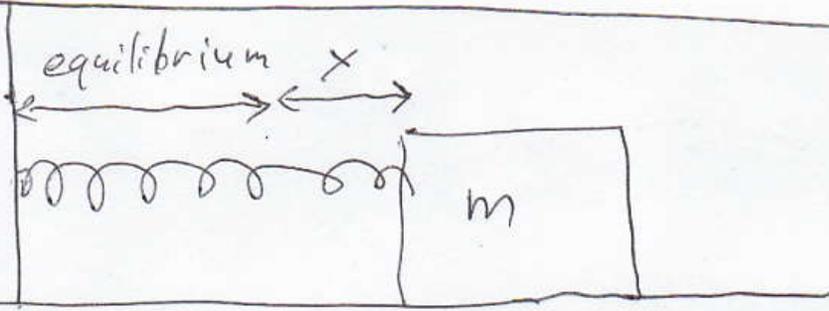


Today (3/20) → Ch. 14. (Oscillations)  
(3/22) → Simulations & exercises

3/27: Last day for approval of  
your simulation ~~choice~~ choice

4/19: Simulations due



$k$  = spring constant



undamped oscillation:  $F = -kx$

damped oscillation:  $F = -kx - bv$

↑  
from friction  
inside  
spring

driven oscillation:



undamped:  $F = -kx + F_0 \cos(\omega_0 t + \phi_0)$

damped:  $F = -kx - bv + F_0 \cos(\omega_0 t + \phi_0)$

Resonance:  $\omega_0$  close to  $\omega = \sqrt{\frac{k}{m}}$

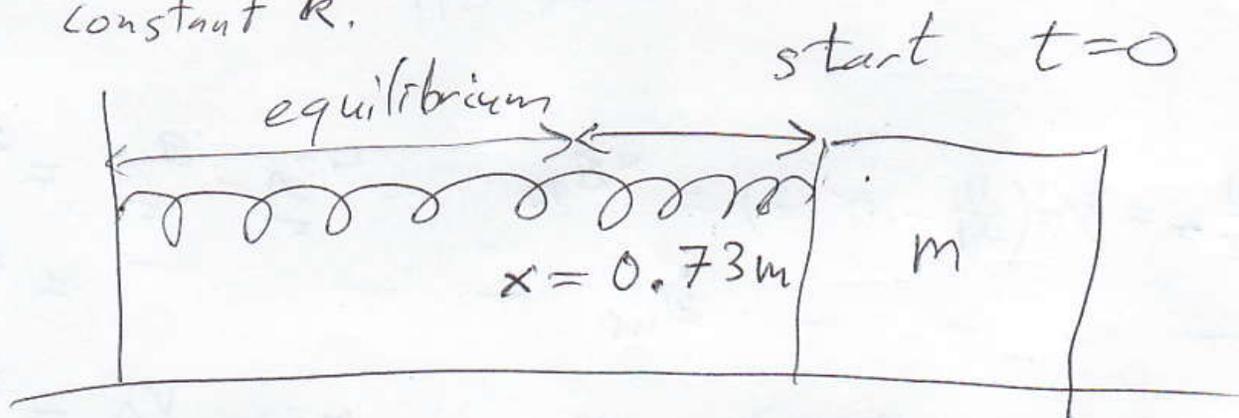
↓  
bigger oscillations

Simulating  $F = -kx$

$$ma = F = -kx$$

$$-\frac{kx}{m} = a = \frac{dv}{dt} \quad v = \frac{dx}{dt}$$

To simulate, pick starting time  $t$ , starting position  $x$ , starting velocity  $v$ ; pick mass  $m$ ; spring constant  $k$ .



$$m = 5.8 \text{ kg}$$

$$v = 0$$

$$k = 15 \text{ N/m}$$

Pick small time increment  $dt$ .

$$-\frac{kx}{m} = a = \frac{dv}{dt}$$

$$v = \frac{dx}{dt}$$

||  
0.1s  
~~0.1s~~

Program:  $a = -k * x / m$

$$dv = a * dt$$

$$v = v + dv$$

$$dx = v * dt$$

$$x = x + dx$$

$$t = t + dt$$

Repeat

Mathematical analysis =

$$-\frac{kx}{m} = a = \frac{dv}{dt} = \frac{d^2x}{dt^2}$$

$$\frac{d^2}{dt^2} \left( \overset{\substack{\text{amplitude} \\ \downarrow}}{A} \cos \left( \overset{\substack{\text{rad} \\ \uparrow}}{\omega t} + \overset{\substack{\text{rad} \\ \uparrow}}{\phi}} \right) \right)$$

measured  
in meters

angular  
frequency  
rad/s

phase  
shift  
tells  
you  
where  
you

$$A > 0$$

$$\phi, \varphi, \Phi$$

~~$\frac{d^2x}{dt^2}$~~

$$\begin{aligned}
& \frac{d}{dt} \left( \frac{d}{dt} (A \cos(\omega t + \phi)) \right) \\
&= A \frac{d}{dt} \left( \frac{d}{dt} \cos(\omega t + \phi) \right) \\
&= A \frac{d}{dt} \left( -\sin(\omega t + \phi) \cdot \underbrace{\frac{d}{dt}(\omega t + \phi)}_{\omega} \right) \\
&= -A\omega \frac{d}{dt} \sin(\omega t + \phi) \\
&= -A\omega \cos(\omega t + \phi) \underbrace{\frac{d}{dt}(\omega t + \phi)}_{\omega} \\
&= -A\omega^2 \cos(\omega t + \phi) \\
&= -\omega^2 (A \cos(\omega t + \phi))
\end{aligned}$$

$$x = A \cos(\omega t + \phi)$$

$$\Downarrow$$

$$a = d^2x/dt^2 = -\omega^2 x$$

Compare to:  $a = -kx/m$

$$\omega = \sqrt{\frac{k}{m}}$$

1 cycle =  $2\pi$  radians

angular frequency  $\omega =$  # radians  
~~per second~~ per second

frequency  $f = \frac{\omega}{2\pi} =$  # cycles

(Other units for  $f$  &  $\omega$  ~~are possible~~  
are possible, like rpm (revolutions per  
minute).) per  
second  
Hertz

period  $T = \frac{1}{f} = \frac{2\pi}{\omega} =$  Hz  
time/cycle

(Other units, like minutes, hours, etc.  
are possible for  $T$ .)

seconds

$$T = \frac{2\pi}{\sqrt{k/m}} = 2\pi \sqrt{m/k}$$

$$k = 150 \text{ N/m} \quad m = 5.8 \text{ kg}$$

$$\text{Simulation: } T = 1.23 \text{ s}$$

$$\begin{aligned} \text{Theory: } 2\pi \sqrt{m/k} &= 2\pi \sqrt{\frac{5.8 \text{ kg}}{150 (\text{kg} \cdot \text{m/s}^2) / \text{m}}} \\ &= 2\pi \sqrt{\frac{5.8}{150} \text{ s}^2} = 2\pi \sqrt{\frac{5.8}{150}} \text{ s} = 1.2355 \dots \text{ s} \\ &\quad \underbrace{\hspace{1.5cm}}_{2 \text{ sig figs}} \end{aligned}$$

$$ma = F = -kx - bv \quad \text{damped oscillation}$$

$$\frac{d^2x}{dt^2} = -kx - b \frac{dx}{dt}$$

$$x = e^{-\gamma t} A_0 \cos(\omega' t + \phi)$$

A = amplitude exponentially decays

$\gamma$  &  $\omega'$  are solved for...

involves ~~quadratic~~ quadratic equation

$$\gamma = \frac{b}{2m} \quad \& \quad \omega' = \sqrt{\frac{k}{m} - \frac{b^2}{4m^2}}$$