

4/12	4.3
4/14	Review
4/19	Test 3 (3.2, 3.4, 4.1, 4.2, 4.3)
4/21	5.1 & 5.2
4/26	5.3
4/28	5.4
5/3	5.5
5/5	Review
5/12	Test 4

Quiz 4/12 (4.3)

In two dimensions, $L = mrv_{\perp}$.

In 3D, \vec{L} is _____

- A) $\vec{r} \times \vec{p}$
 B) $\vec{p} \times \vec{r}$
 C) $\vec{\omega} \times \vec{r}$
 D) $\vec{r} \times \vec{F}$
- $\frac{1}{2}$ credit for (B)

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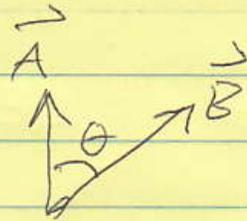
$$\begin{cases} \vec{v} = \vec{\omega} \times \vec{r} \\ \vec{L} = \vec{r} \times \vec{p} \\ \vec{\tau} = \vec{r} \times \vec{F} \end{cases}$$

geometry

$$\vec{C} = \vec{A} \times \vec{B}$$

thumb | hand; arm | fingers

$$|\vec{A} \times \vec{B}| = |\vec{A}| |\vec{B}| \sin \theta$$

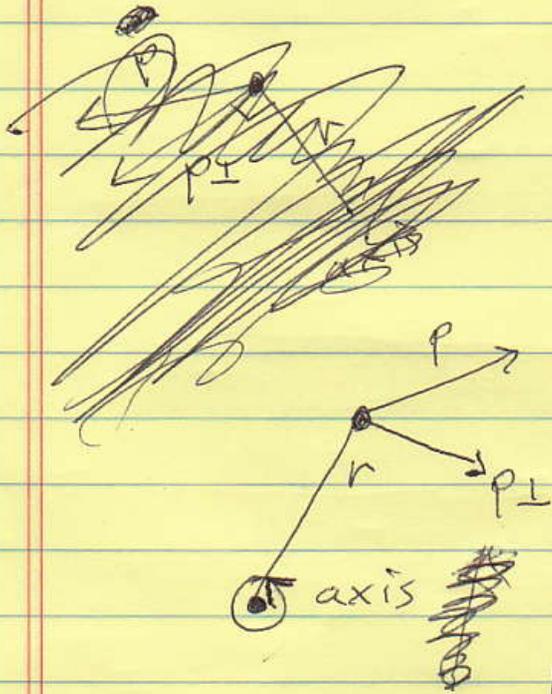


2D

$$|L| = mr|v_{\perp}|$$

$$|L| = r(m|v_{\perp}|)$$

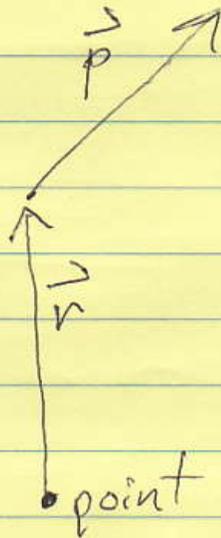
$$|L| = r|p_{\perp}|$$



L negative
if counterclockwise is +

3D

$$\vec{L} = \vec{r} \times \vec{p}$$



$$\vec{L} \otimes$$

\otimes = points in
to paper

\odot = points
out

2D

$$L = I\omega$$

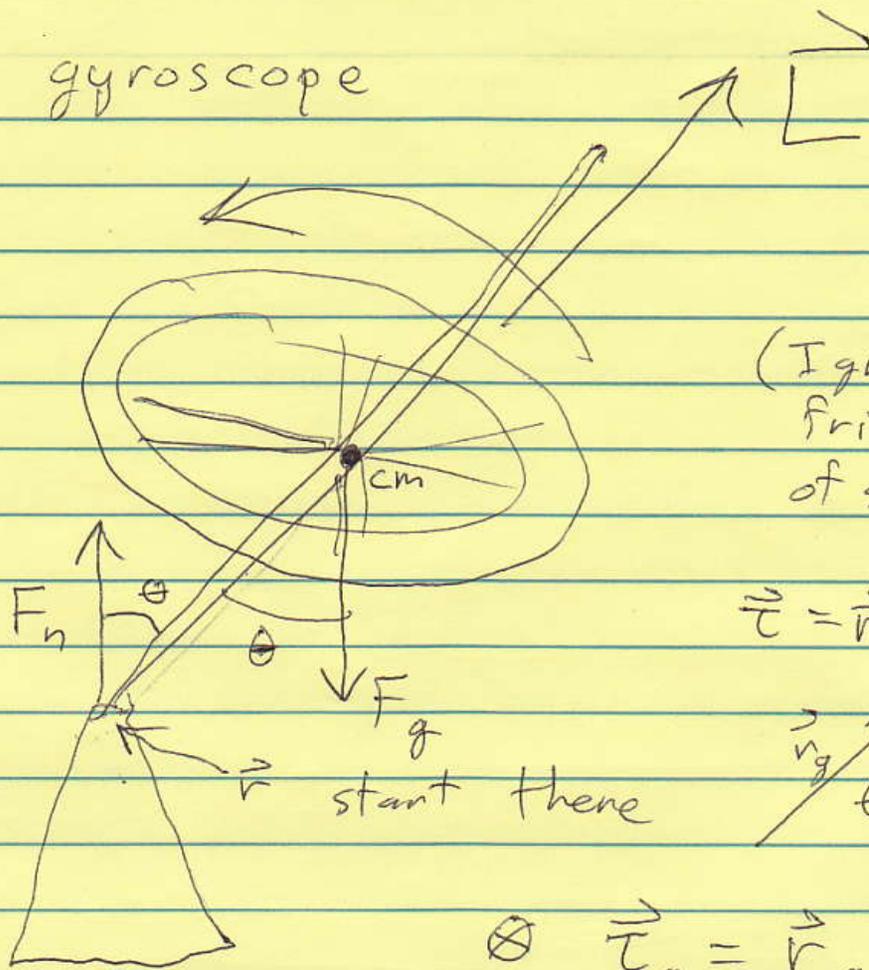
3D

$$\vec{L} = I\vec{\omega}$$



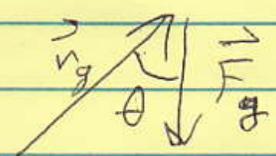
only if the object
is rotating about
an axis of symmetry.

gyroscope



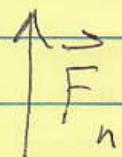
(Ignore friction of simplicity.)

$$\vec{\tau} = \vec{r} \times \vec{F}$$



$$\vec{\tau}_g = \vec{r}_g \times \vec{F}_g$$

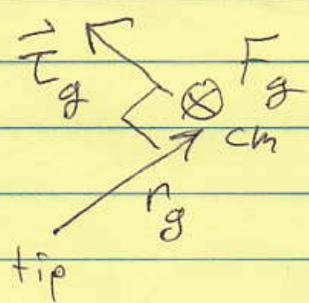
$$|\vec{\tau}_g| = |\vec{r}_g| |\vec{F}_g| \sin \theta$$



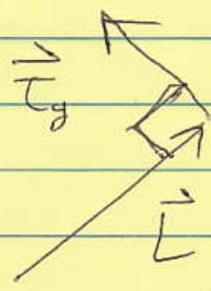
$$\vec{\tau}_n = \vec{0} \times \vec{F}_n = \vec{0}$$

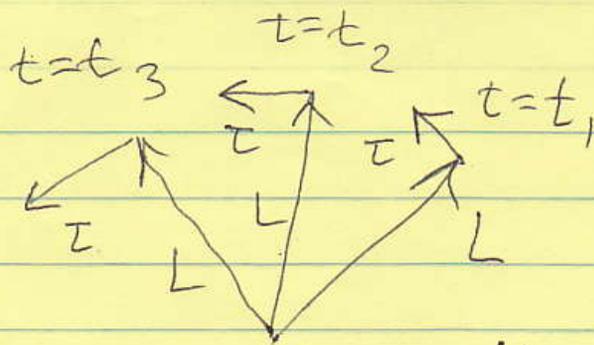
$$\vec{r}_n = \vec{0}$$

overhead view



$$\vec{\tau}_g = \frac{d\vec{L}}{dt}$$

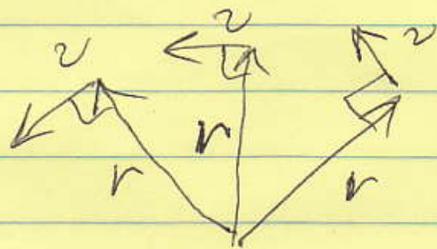




over head view

time for 1 precession cycle is $\frac{2\pi L_{\text{horizontal}}}{\tau}$

Similar to uniform circular motion:



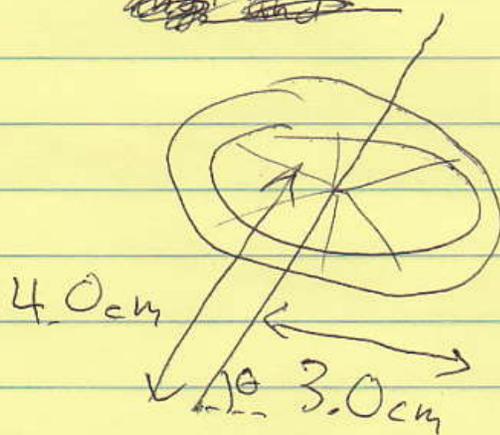
$$v = \frac{2\pi r}{T}$$

$$T = \frac{2\pi r}{v}$$

~~Estimate mass, radius,~~

~~and~~

HW



Assume all mass in ring

$$\theta = 70^\circ$$

If it takes 0.45 seconds for one precession cycle, then find ω .